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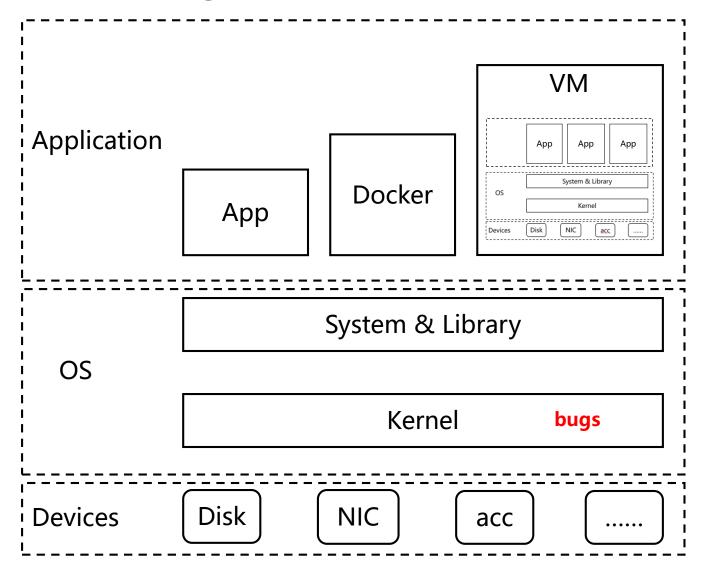
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► 01 Background



Kernel Bugs

- > Kernel Live patch to fix the bug
 - > No live patch for some bug
 - Manager Different
- > Live migration APP/VM & Reboot
 - > No way to the pass-thought device
 - > Large memory to transmit

For Example

Machine: Bare-Metal Server Kunpeng 920

Memory: 380G

Application: Mysql (DB)

* Different to transmit some memory



► 1.1 Instant OS Updates via Userspace Checkpoint-and-Restart

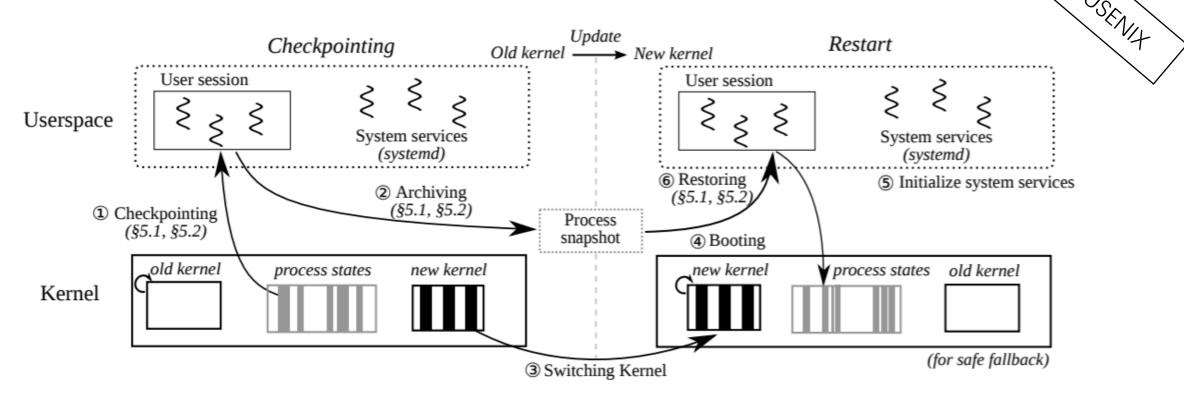
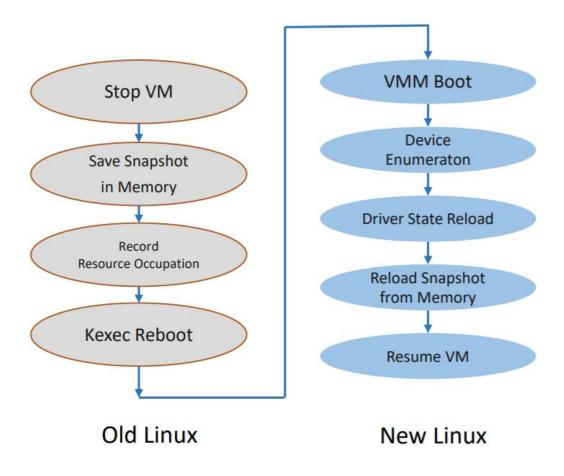


Figure 2: Overview of KUP's updating procedures. KUP first checkpoints user's processes ①, and archives their snapshots ②. After checkpointing selected processes in a user's current session, KUP replaces the old kernel to the new kernel image ③, and finally switches to the new kernel ④. After the new kernel boots, KUP first initializes its system daemons ⑤, and finally restores snapshots of user applications ⑥.



► 1.2 Seamless Cloud System Upgrade with VMM fast Restart

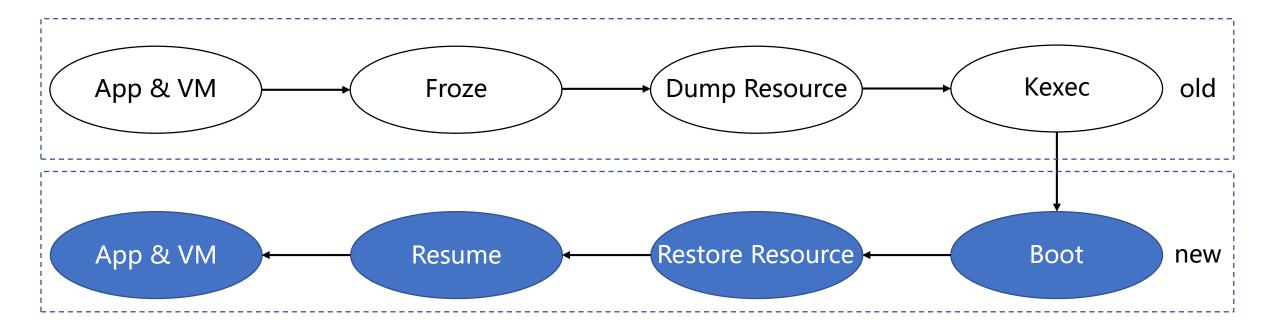
High Level Flow



- Save Snapshot in Memory (in old Linux) & VM Quit
 - DAX filesystem in DRAM-as-PMEM
 - Don't free HW resources (IRTE, etc.)
- Record Resource Occupation
 - Device list, memory, etc.
- KEXEC Reboot
 - No hardware clobber in driver shutdown
- VMM Boot (new Linux)
 - Reserve resources
- Device Enumeration
 - No hardware clobber in PCI enumeration
 - No native driver attaching
- Driver State Reload
 - IOMMU driver reload state
- Reload Snapshot from Memory (in new Linux)
 - Re-enable DAX filesystem in DRAM-as-PMEM
- Resume VM
 - Reload DMA mapping
 - Re-enable MSI/MSIX



▶ 02 Froze/Resume the Application



QEMU: qemu save/restore CRIU: criu dump/restore DMTCP: dmtcp save/restore

^{*} Migration the Application/VM to the Same Machine, the Machine exist at the different time



► 03 Keep Memory

User-space

Kernel

C/R API

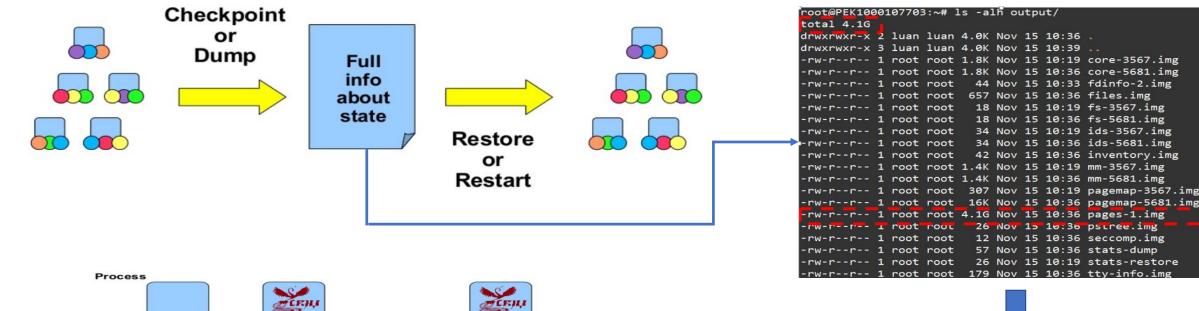
Dump:

ptrace

syscalls

/proc netlink

kmod



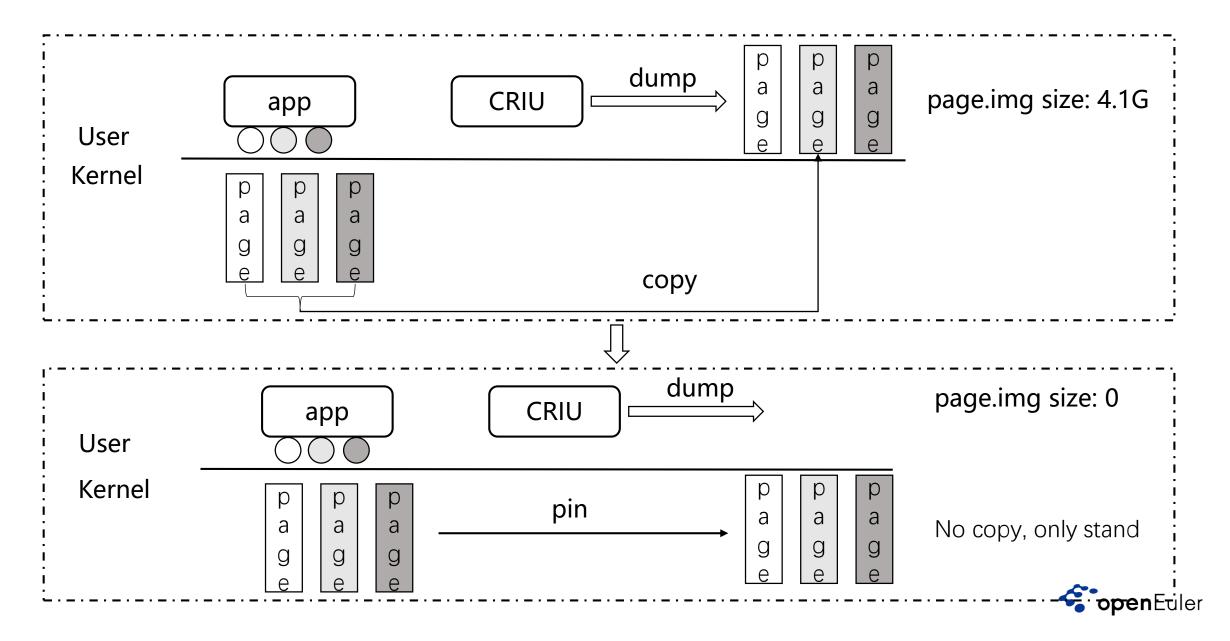
Restore: - syscalls



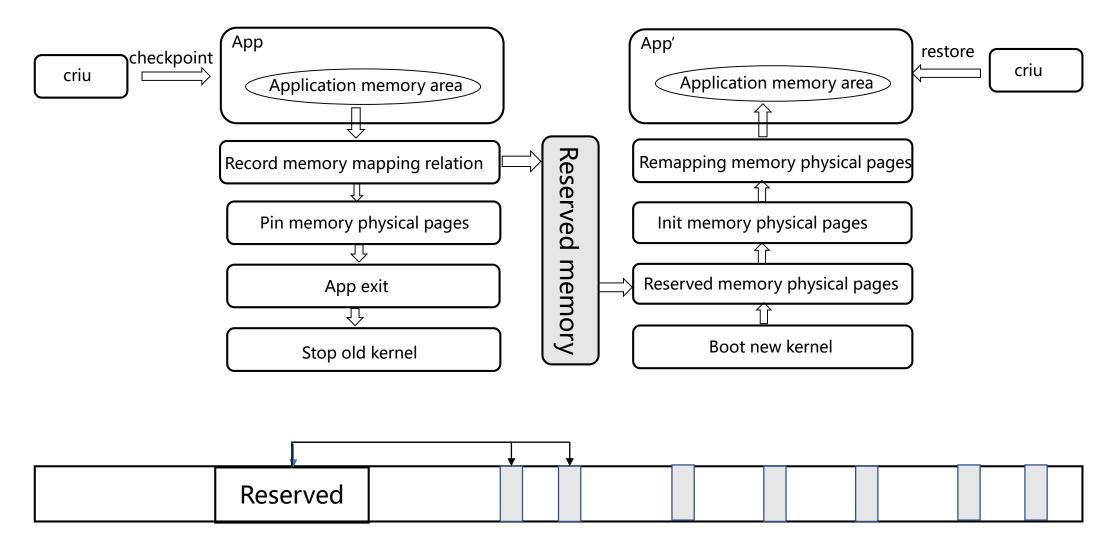
poor performance. For example will write 4.1G memory copy into disk.
No copy and no write, only keep the app into memory (Pin memory).



► 3.1 Pin application memory

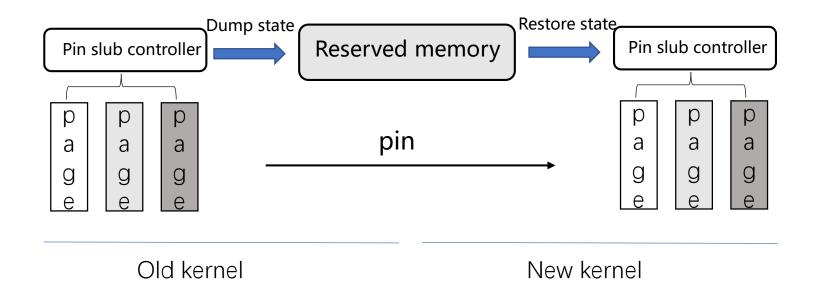


➤ 3.2 keep user memory unchanged in new kernel





► 3.3 keep kernel memory unchanged in new kernel

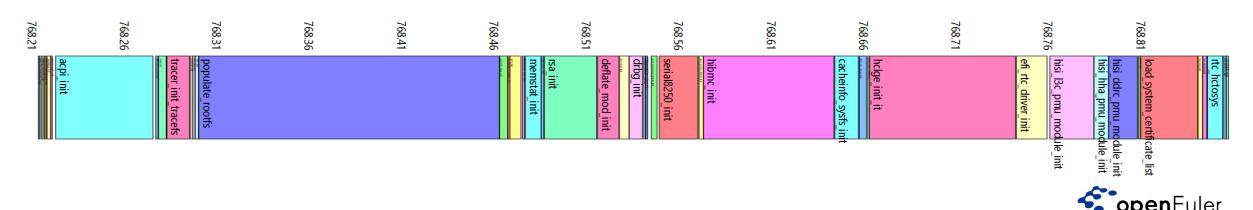




^{*}Create pin slub controller to manage the old kernel pages which need to keep constant While booting the new kernel.

► 04 Kernel Fast Boot

- CPU currently booting
- Pre decompress kernel & initrd
- Memory Defer initialization
- Deferring device driver probe
- Deferring device initialization
- Avoid unless device scanning
- NIC PHY issue



► 4.1 CPU Parallel booting

> Current CPU sequence boot, each ARM core boot will elapse 0.036s.

```
[ 2.796042] Detected VIPT I-cache [ 2.796078] GICv3: CPU81: found re [ 2.796097] GICv3: CPU81: using al [ 2.796155] CPU81: Booted secondar [ 2.836491] Detected VIPT I-cache [ 2.836527] GICv3: CPU82: found re [ 2.836546] GICv3: CPU82: using al [ 2.836603] CPU82: Booted secondar [ 2.876940] Detected VIPT I-cache [ 2.876977] GICv3: CPU83: found re [ 2.876996] GICv3: CPU83: using al [ 2.877053] CPU83: Booted secondar
```

Modify CPU booting. Parallel CPU initiation will shorter the duration (0.0004s).



► 4.2 Pre decompress kernel & initrd

- > Decompress bzlmage to Image(vmlinux) before kexec
- > Enhance kexec-tools to support for original kernel image
- > Decompress initramfs.gz before kexec
- > Unpack initramfs to ramfs in RAM before kexec



► 4.3 Memory Defer initialization

mm: parallelize deferred init memmap()

```
mm: parallelize deferred_init_memmap()
```

Deferred struct page init is a significant bottleneck in kernel boot. Optimizing it maximizes availability for large-memory systems and allows spinning up short-lived VMs as needed without having to leave them running. It also benefits bare metal machines hosting VMs that are sensitive to downtime. In projects such as VMM Fast Restart[1], where guest state is preserved across kexec reboot, it helps prevent application and network timeouts in the guests.

Multithread to take full advantage of system memory bandwidth.

```
Intel(R) Xeon(R) Platinum 8167M CPU @ 2.00GHz (Skylake, bare metal) Intel(R) Xeon(R) CPU E5-2699 v3 @ 2.30GHz (Haswell, bare metal)
 2 nodes * 26 cores * 2 threads = 104 CPUs
 384G/node = 768G memory
```

2 nodes * 18 cores * 2 threads = 72 CPUs 128G/node = 256G memory

	kernel bo	oot	deferred init			kernel boot 		deferred init	
node% (thr)	1. 7% 34. 9% 39. 9% 39. 2% 39. 3% 39. 0%	time_ms (stdev) 4089.7 (8.1) 4019.3 (1.5) 2662.7 (2.9) 2459.0 (3.6) 2485.0 (29.7) 2482.7 (25.7) 2495.7 (5.5) 2443.7 (3.8)	speedup 3. 8% 79. 9% 91. 2% 90. 4% 90. 3% 89. 4% 92. 3%	time_ms (stdev) 1785.7 (7.6) 1717.7 (11.8) 359.3 (0.6) 157.0 (0.0) 172.0 (28.6) 173.7 (30.0) 190.0 (1.0) 138.0 (1.0)	3% (1) 11% (4) 25% (9) 36% (13) 50% (18) 75% (27)	speedup 0. 3% 25. 6% 30. 7% 31. 4% 31. 5% 31. 7% 32. 0%	time_ms (stdev) 1680.0 (4.6) 1675.7 (4.5) 1250.7 (2.1) 1164.0 (17.3) 1152.7 (10.8) 1150.7 (9.3) 1148.0 (5.6) 1142.3 (4.0)	speedup -0. 2% 67. 9% 81. 8% 84. 0% 83. 9% 84. 5% 85. 6%	time_ms (stdev) 627.0 (4.0) 628.0 (3.6) 201.0 (0.0) 114.3 (17.7) 100.3 (17.9) 101.0 (14.1) 97.3 (6.4) 90.0 (1.0)

► 4.4 Deferring device driver probe

drivercore: add driver probe deferral mechanism

drivercore: Add driver probe deferral mechanism

Allow drivers to report at probe time that they cannot get all the resources required by the device, and should be retried at a later time.

```
module.async_probe [KNL]
Enable asynchronous probe on this module.
```

```
deferred_probe_timeout=

[KNL] Debugging option to set a timeout in seconds for deferred probe to give up waiting on dependencies to probe. Only specific dependencies (subsystems or drivers) that have opted in will be ignored. A timeout of 0 will timeout at the end of initcalls. This option will also dump out devices still on the deferred probe list after retrying.
```



► 4.5 Deferring device initialization

> Deferring device driver, only defer the driver for the same, but sometime we only want to defer some device probe, for example:

```
0.860672] hns3 0000:7d:00.0: The firmware version is 1.8.12.3
0.940779] hns3 0000:7d:00.0: hclge driver initialization finished.
0.941897] hns3 0000:7d:00.1: The firmware version is 1.8.12.3
1.020563] hns3 0000:7d:00.1: hclge driver initialization finished.
1.021641] hns3 0000:7d:00.2: The firmware version is 1.8.12.3
1.100787] hns3 0000:7d:00.2: hclge driver initialization finished.
1.101882] hns3 0000:7d:00.3: The firmware version is 1.8.12.3
1.180567] hns3 0000:7d:00.3: hclge driver initialization finished.
```

> Deferring device initialization when the device add system, we only active one hns3 NIC, other will be defer.



► 4.6 Avoid unless device scanning

Some device no change, no rescan the device. We store some initialize information into reserve memory, use the information when reinitialize the device.

- PCI Scan information
- SATA disk scan information
- **>**



► 4.7 NIC PHY issue

➤ When NIC reset PHY and reload firmware, the NIC transports no package input system until 3-5s later. No network, the downtime of the application will be poor.

```
Link detected: yes 16:18:42
Link detected: no 16:18:43
Link detected: no 16:18:44
Link detected: no 16:18:45
Link detected: no 16:18:46
Link detected: no 16:18:47
Link detected: no 16:18:48
Link detected: no 16:18:49
Link detected: no 16:18:50
Link detected: no 16:18:51
Link detected: no 16:18:52
Link detected: no 16:18:53
Link detected: yes 16:18:54
```

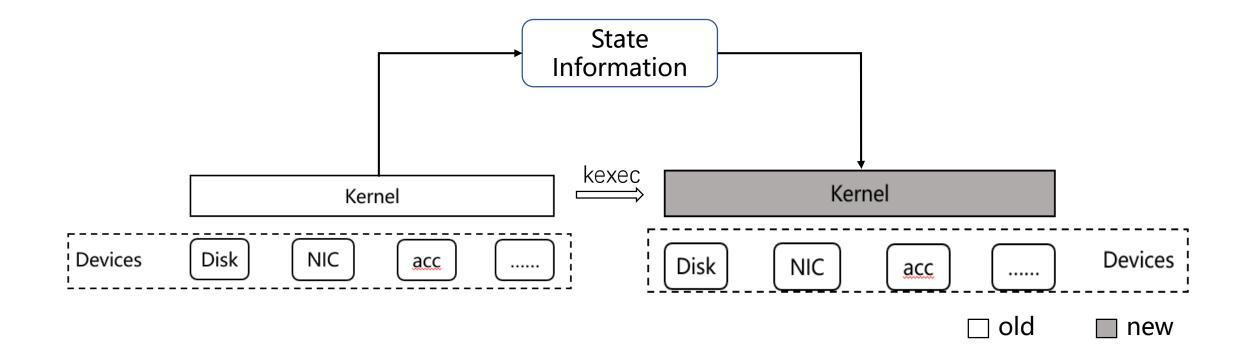
> Modify the driver of the NIC, no reset PHY and reload firmware when quick reboot.

```
[ 4263.380716] icmp: icmp_echo: id=52763, seq=19903 
[ 4263.484684] icmp: icmp_echo: id=52763, seq=19904 
[ 4263.588715] icmp: icmp_echo: id=52763, seq=19905 
[ 4263.692706] icmp: icmp_echo: id=52763, seq=19906 
[ 4263.800706] icmp: icmp_echo: id=52763, seq=19907 
[ 4263.904708] icmp: icmp_echo: id=52763, seq=19908 
[ 4264.008702] icmp: icmp_echo: id=52763, seq=19909 
[ 4264.116695] icmp: icmp_echo: id=52763, seq=19910 
[ 4264.224690] icmp: icmp_echo: id=52763, seq=19911 
[ 4264.328679] icmp: icmp_echo: id=52763, seq=19912
```



^{*} Should sure the state correct, as no reset PHY

► 05 Keep Device State

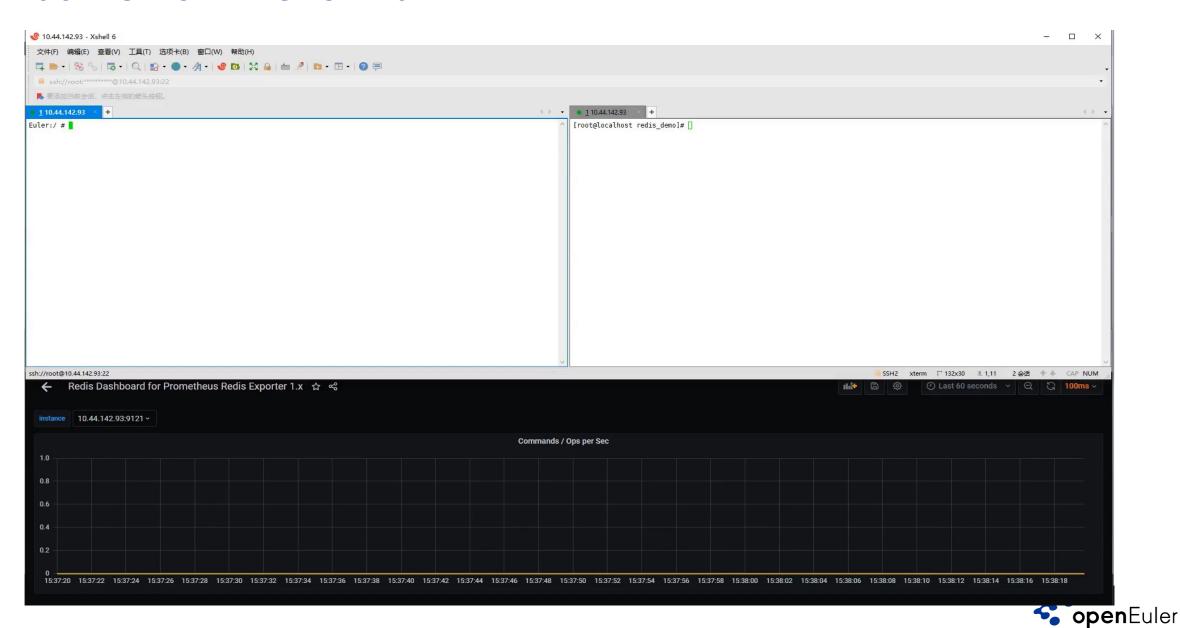


State information: reserve memory to save device state information

* Caution: must concurrent device state and kernel driver information



▶ 06 Demo -- Benchmark



▶ 07 Todo

- Open Source to openEuler
- Replace CRIU with kernel module
- Standard Device State Process
- Faster Kernel boot
- Multi Kernel parallel initialization



Reference

- 1 https://criu.org/Seamless_kernel_upgrade
- 2 https://www.usenix.org/system/files/conference/atc16/atc16_paper-kashyap.pdf
- 3 https://kvmforum2019.sched.com/event/TmvJ/seamless-cloud-system-upgrade-with-vmm-fast-restart-jason-zeng-intel
- 4 https://www.linuxplumbersconf.org/event/4/contributions/281/attachments/216/617/LPC_2019 kernel fastboot on the way.pdf
- 5 http://dmtcp.sourceforge.net/papers/dmtcp.pdf



Q&A

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